Hexagon socket head cap screw (standard) (2) Through hole for mounting gripper

3 Positioning for mounting gripper

4 Threaded hole for mounting truss

(5) Avoidance hole

6 Positioning guide strip (A) Pushing test

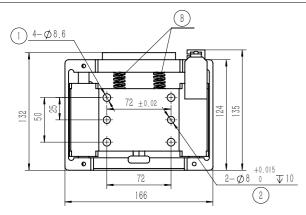
(B) Pushing spring

© Slider assembly

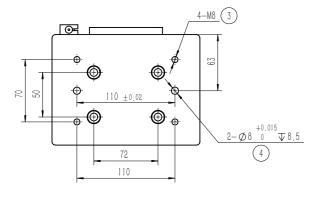
Rotary connecting plate

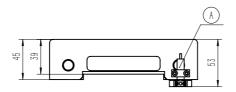
HT-HE40

HT-ZG32



Flexible compensation unit series FOUK-HT





- 1 Through hole for mounting gripper
- 2 Positioning for mounting gripper
- 3 Threaded hole for mounting truss
- 4 Positioning for mounting truss
- (A) Pushing test
- (B) Thrust spring

Note: The standard version of the product does not include the sensor, which is an

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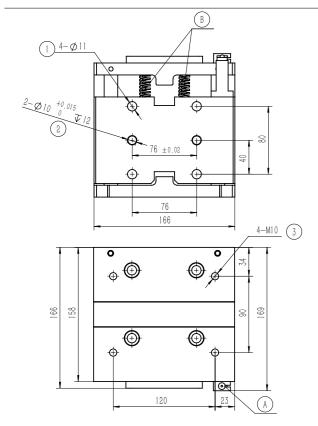
2-Ø6 +0.015 V14

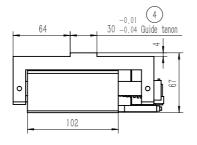
Mounting steps of gripper: 1.First remove (1) through (5) 2.Position on the gripper with the cylindrical locating pin through (3). 3.Fix (D) on the corresponding gripper with the hexagon socket head cap screw through 2. 4. Finally, install and fix the two plates of

C and D with 1 through 5

HT-HE50

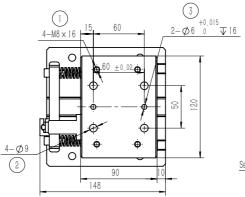
HT-ZG40

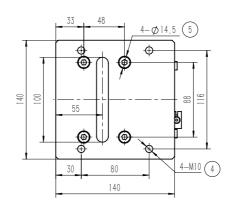


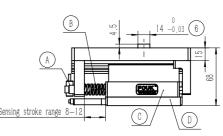


- 1 Through hole for mounting gripper
- 2 Positioning for mounting gripper
- 3 Threaded hole for mounting truss
- 4 Positioning for mounting truss
- (A) Pushing test
- B Thrust spring

Note: The standard version of the product does not include the sensor, which is an optional item.







Mounting steps of gripper: 1.First remove (1) through (5) 2.Position on the gripper with the cylindrical locating pin through (3). 3.Fix (D) on the corresponding gripper with the hexagon socket head cap screw through (2) 4. Finally, install and fix the two plates of

(C) and (D) with (1) through (5)

- Hexagon socket head cap screw (standard)
- (2) Through hole for mounting gripper 3 Positioning for mounting gripper
- 4 Threaded hole for mounting truss
- (5) Avoidance hole
- 6 Positioning guide strip
- A Pushing test
- B Pushing spring
- C Slider assembly
- D Rotary connecting plate